

Conformal prediction

**A not-so-gentle mashup
of oh-so-gentle introductions**

Disclaimer



(NIH)

A tall order

About UQ...

- $X \mapsto \hat{Y} = f(X)$ not enough for *decision making*. Need CIs / ...
 - Bootstrap methods. Cost! Asymptotics & assumptions
 - Asymptotic estimates (e.g. CLT+BE). But real life has **fat tails**...
 - So... go Bayesian or go home?
 - costly, approximations are usually unjustified
 - priors are basically arbitrary, so why trust the posterior?
- ⇒ Need proper **“confidence sets”** with guarantees *based on data* and not on assumptions

The goal of conformal prediction

Given: **supervised trained model** f , and (unseen) **calibration dataset** \mathcal{D}_{cal} i.i.d.

Attach “**UQ / calibration layer**” to f which outputs “good” **prediction sets**

- Regression:
intervals covering true values
- Classification:
discrete sets containing the true class



with high probability

For new (X, Y) compute set $\mathcal{C}(X)$ s.t.

$$\mathbb{P}(Y \in \mathcal{C}(X)) \approx 1 - \alpha \quad (\text{coverage})$$

What we get

Conformal predictor: $\mathcal{C}: \mathcal{X} \rightarrow 2^{\mathcal{Y}}$ with **guaranteed coverage**

- **Distribution-free**
- **Model-agnostic:** works with RFs, GBTs, NNs and any **black-box**
- **Efficiency:** $|\mathcal{C}(X)| \ll |\mathcal{Y}|$ (no trivial solution)
- **Adaptivity:** $|\mathcal{C}(X)|$ depends on the model's uncertainty
- \mathcal{D}_{cal} unseen by f , hence “*split CP*”. Same distribution as $\mathcal{D}_{\text{train}}$

What we get

Conformal predictor: $\mathcal{C}: \mathcal{X} \rightarrow 2^{\mathcal{Y}}$ with **guaranteed coverage**

- $\mathcal{C} = \mathcal{C}(f, \mathcal{D}_{\text{cal}}, \alpha)$
- **Distribution-free**
- **Model-agnostic:** works with RFs, GBTs, NNs and any **black-box**
- **Efficiency:** $|\mathcal{C}(X)| \ll |\mathcal{Y}|$ (no trivial solution)
- **Adaptivity:** $|\mathcal{C}(X)|$ depends on the model's uncertainty
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What this means

- Interpretable? ✓
 - Context for the outputs. Alternatives matter in high-stakes decisions!
 $\{\text{defective ball-bearing, unbalanced wheel}\} \neq \{\text{defective ball-bearing, axle failure}\}$
- Useful for automated decisions? ✓
 - Rigorous, calibrated uncertainty estimates
 - OOD detection
 - ...
- Criterion to select between algorithms (“best” prediction sets)
- And more!

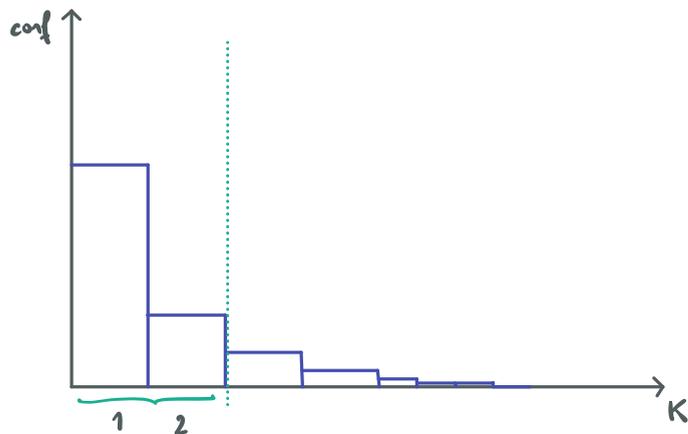
An algorithm for classification

A first idea

$f: \mathcal{X} \rightarrow [0, 1]^K$ classifier. Desired cover. 90%

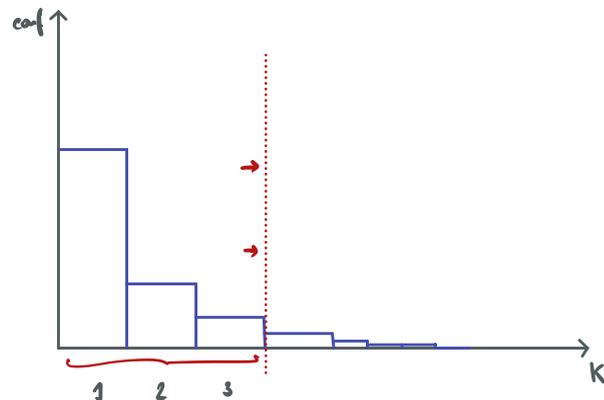
New x' . Sort confidences: $c'_{(1)}, \dots, c'_{(K)}$

($c_{(j)}$ is the j -th order statistic of c)



Include classes $\mathcal{C}(x') := \{f_{(1)}, \dots, f_{(m)}\}$ **while**
 $\sum_{j=1}^m c'_{(j)} < 0.9$

Poorly calibrated (NNs overconfident...)



For every $(x_i, y_i) \in \mathcal{D}_{\text{cal}}$ **calibration set**:

Sum confidences into $s_i := \sum_{j=1}^{m_i} c'_{(j)}$

taking classes until **true** y_i , in position m_i

$\min \hat{q} \in [0, 1]$ s.t. $\hat{\mathbb{P}}(S \leq \hat{q}) \geq 0.9$

$\mathcal{C}(x') := \{f(x')_{(1)}, \dots, f(x')_{(m)}\}$ where

m is s.t. $\sum_{j=1}^m c'_{(j)} < \hat{q}$

Calibrated on unseen data!

Adaptive predictive sets for classification

For each $(x_i, y_i) \in \mathcal{D}_{\text{cal}}$ compute a **conformity score**: $s_i = s(x_i, y_i) := \sum_{j=1}^{m(y_i)} f(x_i)_{(j)}$,

s is the model's *up-to-true-label total confidence*

Look at $\hat{q}_{.9}$, the 90th percentile of s

$$q_{.9} := F_S^{-1}(.9) := \min_q \{\mathbb{P}(S \leq q) \geq .9\}$$

For $\sim 90\%$ of \mathcal{D}_{cal} 's samples f has up-to-true-label confidence below $\hat{q}_{.9}$

Define $\mathcal{C}(x') := \{y_1, \dots, y_{m'} : \sum_{j=1}^{m'} f(x')_{(j)} \leq \hat{q}_{.9}\}$

Adding classes until the total confidence reaches $\hat{q}_{.9}$ results in $\sim 90\%$ of the sets $\mathcal{C}(x_i)$ including the true class

Profit!

$$\mathbb{P}(Y' \in \mathcal{C}(X')) \approx .9$$



A simpler algorithm

1. For each $(x_i, y_i) \in \mathcal{D}_{\text{cal}}$ compute a **conformity score**: $s_i = s(x_i, y_i) := 1 - f(x_i)_{y_i}$,
 S is the *model's "uncertainty" for the correct class*

Look at the 90th percentile $\hat{q} = \hat{q}_{.9}$

$\mathbb{P}(S \leq \hat{q}_{.9}) \geq .9$ means that:

**f has confidence $\geq 1 - \hat{q}$ for
90% of \mathcal{D}_{cal} 's labels**

2. In other words:

$\sim 90\%$ of \mathcal{D}_{cal} 's labels have **true-class uncertainty** below $\hat{q}_{.9}^{(n)}$

3. Define
$$\mathcal{C}(x') := \{y \in \mathcal{Y} : s(x', y) \leq \hat{q}_{.9}^{(n)}\} = \{y : f(x')_y \geq 1 - \hat{q}_{.9}^{(n)}\}$$

4. **Profit!**



The general recipe

What we did:

1. Take a **heuristic notion** of uncertainty associated to f

Ex: softmax outputs

2. Define a **conformal score** $s(x, y) \in \mathbb{R}$ for all (x, y) and compute over \mathcal{D}_{cal}

Higher is worse

3. Compute a high **conformal quantile** $\hat{q} = \hat{q}_{1-\alpha}$

$(1 - \alpha)$ fraction of samples in \mathcal{D}_{cal} have score $\leq \hat{q}$

4. Define $\mathcal{C}(x') := \{y: s(x', y) \leq \hat{q}\}$

5. Then $\mathbb{P}(Y' \in \mathcal{C}(X')) \approx 1 - \alpha$

(theorem)



The fundamental theorem

Theorem. ([VGS05])

Let $\{(X_i, Y_i)\}_{i=1}^{n+1}$ be **exchangeable**. Define $\hat{q} := \hat{q}_{1-\alpha}^{(n)} := \hat{F}_{s,n}^{-1}\left(\frac{\lceil (n+1)(1-\alpha) \rceil}{n}\right)$. Then $\mathcal{C} = \mathcal{C}_{\hat{q}}: \mathcal{X} \rightarrow 2^{\mathcal{Y}}$ constructed as

$$\mathcal{C}(X) := \{y \in \mathcal{Y}: s(X, y) \leq \hat{q}\}$$

fulfills

$$1 - \alpha \leq \mathbb{P}(Y_{n+1} \in \mathcal{C}(X_{n+1})) \leq 1 - \alpha + \frac{1}{n+1},$$

for f, α, n arbitrary.

Key property: Exchangeability implies that S_{n+1} is **indistinguishable** from the other S_i . It has equal probability of falling between any two conformal scores.

$$\mathbb{P}(S_{n+1} \leq S_k) = \frac{k}{n+1}.$$

But... how good can this be?

It's not magic...

- Constant scores? Useless sets
- Random scores? Useless sets
- Ranking of scores does not reflect model error? Useless sets
- Informative scores? ✓
- Adapted loss functions? ✓
- Heavy tails? ✓ Predictive sets will be larger

**Beyond the
discrete**

Can we do the same for regression?

1. $Y = f(X) + \varepsilon \in \mathbb{R}$ regression model. Uncertainty heuristic: **residuals** $|Y - \hat{f}(X)|$
2. Compute **conformal scores** $s(x_i, y_i) := |y_i - f(x_i)|$ over \mathcal{D}_{cal}

3. Form
$$\hat{q}_{1-\alpha} = \min \left\{ q: \frac{|\{i: s_i \leq q\}|}{n} \geq 1 - \alpha \right\}$$

4. Define
$$\mathcal{C}(x') := \{y \in \mathbb{R}: s(x', y) \leq \hat{q}_{1-\alpha}\} = [\hat{f}(x') - \hat{q}_{1-\alpha}, \hat{f}(x') + \hat{q}_{1-\alpha}]$$

5. Profit?

Constant size for prediction interval

Why do we learn the mean $\mathbb{E}[Y|X]$, when **we care about quantiles**?

An idea

- Recall: CDF of $Y|X$ is $\mathbb{P}(Y \leq y|X)$
 α -th **conditional quantile function** $t_\alpha(X) := \inf \{y \in \mathbb{R}: \mathbb{P}(Y \leq y|X) \geq \alpha\}$
- The **conditional prediction interval**

$$\mathcal{C}(X) = [t_{\alpha/2}(X), t_{1-\alpha/2}(X)]$$

trivially satisfies

$$\mathbb{P}(Y \in \mathcal{C}(X)|X) = 1 - \alpha$$

- Alas... we don't have access to the CDF of $Y|X$
So we can **learn the quantiles** instead **and conformalize** (finite sample guarantees)

Conformalized Quantile Regression

- Use **pinball loss** ρ_α to learn quantiles $(\hat{t}_{\alpha/2}, \hat{t}_{1-\alpha/2})$

$$\rho_\alpha(y, \hat{y}) = \begin{cases} \alpha (y - \hat{y}) & \text{if } y > \hat{y} \\ (1 - \alpha) (\hat{y} - y) & \text{otherwise} \end{cases}$$

- Use **signed distance to the closest quantile** as score

$$s(x, y) := \max \{ \hat{t}_{\alpha/2}(x) - y, y - \hat{t}_{1-\alpha/2}(x) \}$$

- Compute $\hat{q} = \hat{q}_{1-\alpha}$

- Same prediction rule:

$$\begin{aligned} \mathcal{C}(x') &= \{y \in \mathbb{R}: s(x', y) \leq \hat{q}\} \\ &= [\hat{t}_{\alpha/2}(x') - \hat{q}, \hat{t}_{1-\alpha/2}(x') + \hat{q}] \\ &\supseteq [\hat{t}_{\alpha/2}(x'), \hat{t}_{1-\alpha/2}(x')] \end{aligned}$$

Conformalized Quantile Regression

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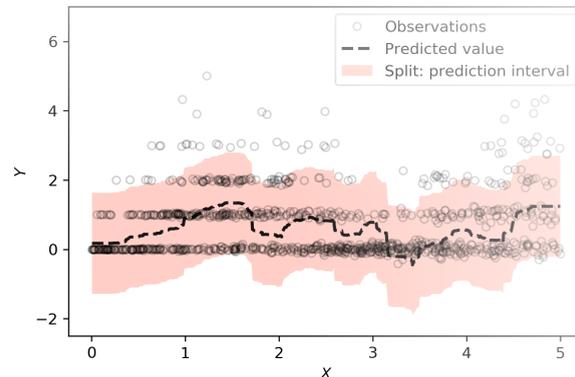
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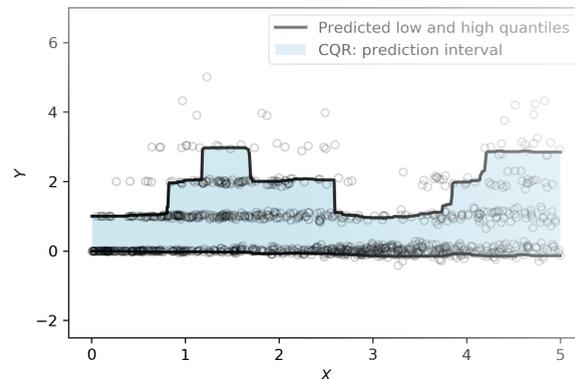
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(a) Split: Avg. coverage 91.4%; Avg. length 2.91.



(c) CQR: Avg. coverage 91.06%; Avg. length 1.99.

[RPC19]

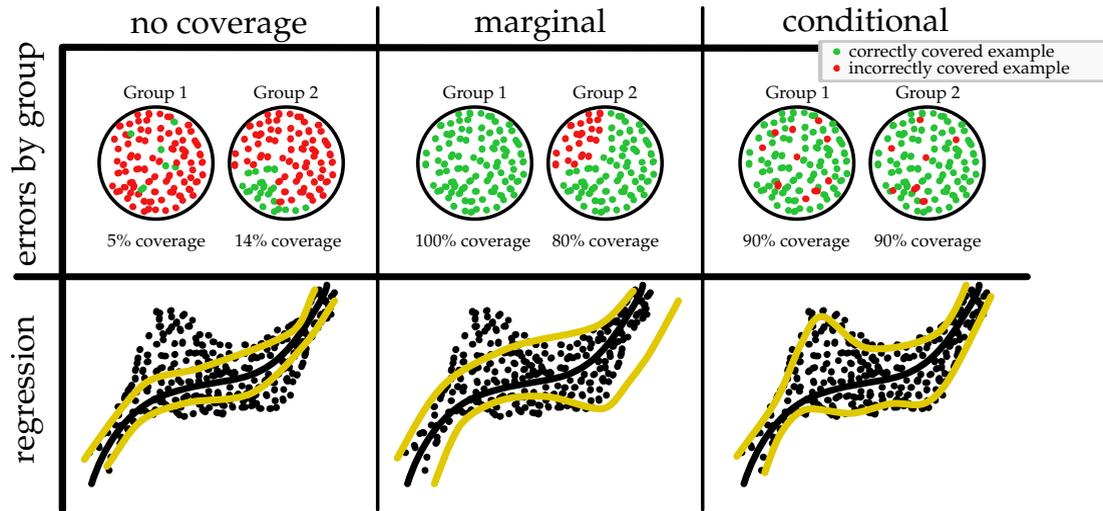
**Potential
stumbling blocks**

Difficulty #1: Marginal vs conditional

$\mathbb{P}(Y \in \mathcal{C}(X)) \approx 1 - \alpha$ is a *marginal* guarantee

- One usually wants a stronger **conditional guarantee** $\mathbb{P}(Y \in \mathcal{C}(X) | \mathcal{D})$
- Not conditional on $\mathcal{D}_{\text{cal}}, \mathcal{D}_{\text{train}}$
 - ⇨ Fluctuations wrt. $1 - \alpha$
 - ⇨ Need n large enough (see later, and [Vov12])
- Not conditional on groups
 - ⇨ **Coverage unbalanced** in \mathcal{X} or \mathcal{Y} (only “easy” samples) $C = \mathbb{E}[\mathbb{1}\{Y \in \mathcal{C}(X)\}]$
 - ⇨ Check coverage separately over a partition of \mathcal{X} or \mathcal{Y} $\hat{C} = \hat{\mathbb{E}}_{\mathcal{D}_{\text{val}}}[\mathbb{1}\{Y_i \in \mathcal{C}(X_i)\}]$
 - ⇨ Changes to the score, many techniques.

Conditional coverage



[AB22]

Measuring coverage

$$C = \mathbb{E}[\mathbb{1}\{Y \in \mathcal{C}(X)\}]$$

1. Cross-validation over $\mathcal{D}_{\text{cal}}, \mathcal{D}_{\text{val}}$ of **empirical coverage**

$$\hat{C} = \frac{1}{|\mathcal{D}_{\text{val}}|} \sum_{x, y \in \mathcal{D}_{\text{val}}} \mathbb{1}\{y \in \mathcal{C}_{\mathcal{D}_{\text{cal}}}(x)\}$$

Mean should concentrate around $1 - \alpha$

Bad \hat{C} is a good indicator of *distribution shift* (more later)

2. Distribution of \hat{C} is known [AB22, App. C]

Good checks available, formulas to look for errors. Use moments to verify implementation

3. Verify conditional coverage with **feature-stratified** or **size-stratified** coverage

Conditional guarantees

- **Feature-balanced CP** [Vov12, AB22]

1. Want: $\mathbb{P}(Y' \in \mathcal{C}(X') | X'_1 = g) \approx 1 - \alpha$ for all $g \in \{1, \dots, G\} = \text{range}(X_1)$

2. Stratify by group: $s_i^{(g)}, \hat{q}^{(g)}$

3. $\mathcal{C}(x) := \{y: s(x, y) \leq \hat{q}^{(x_1)}\}$



- **Class-conditional CP** [Vov12, AB22]

1. Want: $\mathbb{P}(Y' \in \mathcal{C}(X') | Y = y) \approx 1 - \alpha$ for all $y \in \mathcal{Y}$

2. Stratify by class: $s_i^{(k)}, \hat{q}^{(k)}$

3. $\mathcal{C}(x) := \{y: s(x, y) \leq \hat{q}^{(y)}\}$



Difficulty #2: distribution shift

Distribution shift, $\{(X_i, Y_i)\}_{i=1}^{n+1}$ non exchangeable

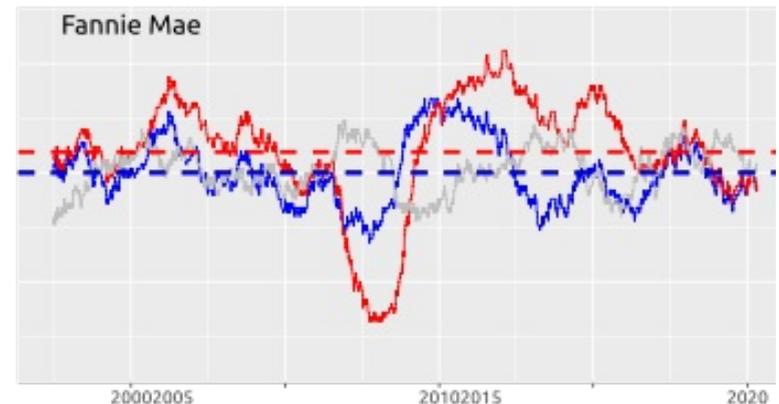
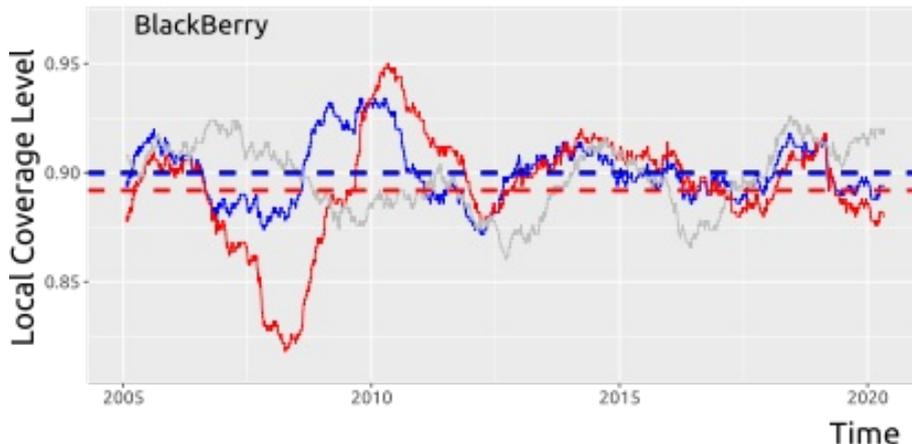
Time series, streaming data, finite data, interactive systems, ...

Adaptive CP [GC21]: Compute $\alpha_{n+1}, \alpha_{n+2}, \dots$, with $\begin{cases} \text{increase } \alpha_t & \text{if } Y_t \in \mathcal{C}(X_t) \\ \text{decrease } \alpha_t & \text{if } Y_t \notin \mathcal{C}(X_t) \end{cases}$

$$\alpha_{t+1} := \alpha_t + \gamma(\alpha - \text{err}_t), \text{ where } \text{err}_t := \mathbb{1}_{\mathcal{C}_t}(Y_t)$$

And reestimate $\hat{q}_{1-\alpha}$.

Also see [GC22, BCRT22]



Difficulty #2: distribution shift

Distribution shift, $\{(X_i, Y_i)\}_{i=1}^{n+1}$ non exchangeable

Time series, streaming data...

NEXCP [BCRT22]

- **Fixed, non-negative weights** $\sum w_i = 1$ for conformal scores (decay)
- Computes $\hat{q}_{1-\alpha}^{(n, w_i)}$ wrt. **weighted empirical distribution** $\hat{F}_{s, w}^{(n)} = \frac{1}{n+1} \sum w_i \delta_{s_i}$
- $\mathcal{C}(x_{n+1}) := \{y: s(x_{n+1}, y) \leq \hat{q}_{1-\alpha}^{(n, w_i)}\}$

More difficulties

- In some domains, coverage is not the right notion!
 - ⇒ **Conformal Risk Control** [ABF+22]
- Data waste
 - ⇒ **Full** conformal prediction
 - ⇒ **jackknife+**

How good is my CP?

- Adaptivity: not guaranteed but essential. Smallest average $|\mathcal{C}(X)|$ not enough
- **Histogram** of $|\mathcal{C}(x_i)|$ informative but not conclusive
- Coverage checks: formulae to look for errors [AB22, §3]
 - Analytic expression for sample coverage
 - Use moments to verify implementation
 - Bad coverage is a good indicator of distribution shift
- Dependence on the calibration set:

$$\mathbb{P}(Y' \in \mathcal{C}(X') | \mathcal{D}_{\text{cal}}) \sim \text{Beta}(n + 1 - m, m), \quad m := \lfloor (n + 1) \alpha \rfloor$$

Invert the CDF to compute n for δ, ε . See [Vov12] for this and more

Extensions

A long list

- Group-balanced CP: ensure per-group coverage
- Class-conditional CP: ensure per-class coverage
- Conformal risk control: minimise false negative rate, maximise “fairness”, ... [ABF+22]
- Outlier detection: p -values instead of the 3σ hack [BAL+21]
- CP under distribution shift: real data, streaming data, ... [BCRT22, GC22, GC21]
- CP without exchangeability.
- Joint optimization: “smooth sorting”, increases CW-efficiency [SDCD22]

Recap

The core idea

1. Take a **heuristic notion** of uncertainty associated to f
2. Define a **conformal score** $s(x, y) \in \mathbb{R}$ and compute over \mathcal{D}_{cal}
3. Compute a high **conformal quantile** $\hat{q} = \hat{q}_{1-\alpha}^{(n)}$
4. Define
$$\mathcal{C}(x') := \{y: s(x', y) \leq \hat{q}\}.$$
5. Then:
$$\mathbb{P}(Y' \in \mathcal{C}(X')) \approx 1 - \alpha.$$

Methods for classification and regression. Trivial to implement. Ready-to-use examples

Simple techniques to verify implementation

Adaptive and heuristic methods for time series

Applications to OOD and multi-task

Can optimize arbitrary risks

The core issues

1. Lack of conditional guarantees
2. Efficiency (class-wise and group-wise)
3. Distribution shift
4. ...

Happy conformalizing!

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Sources~>

A learning path

1. Videos: **excellent** tutorials by Angelopolous & Bates (YouTube)
2. A&B's **easy and comprehensive introduction** [AB22]
(Many of the references in this talk are introduced here)
3. NeurIPS 2022 talk by Candès on **distribution shift**, NEXCP and related papers
4. **Awesome Conformal Prediction** on github for ALL the pointers (too many)
5. Some of Vovk's work, e.g. conditional guarantees (and lack thereof) [Vov12]
6. Look for papers by Angelopoulos, Bates, Candès, Jordan, Lei, Tibshirani, Wasserman, ...
7. [oci] **TRANSFERLAB?**

References

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